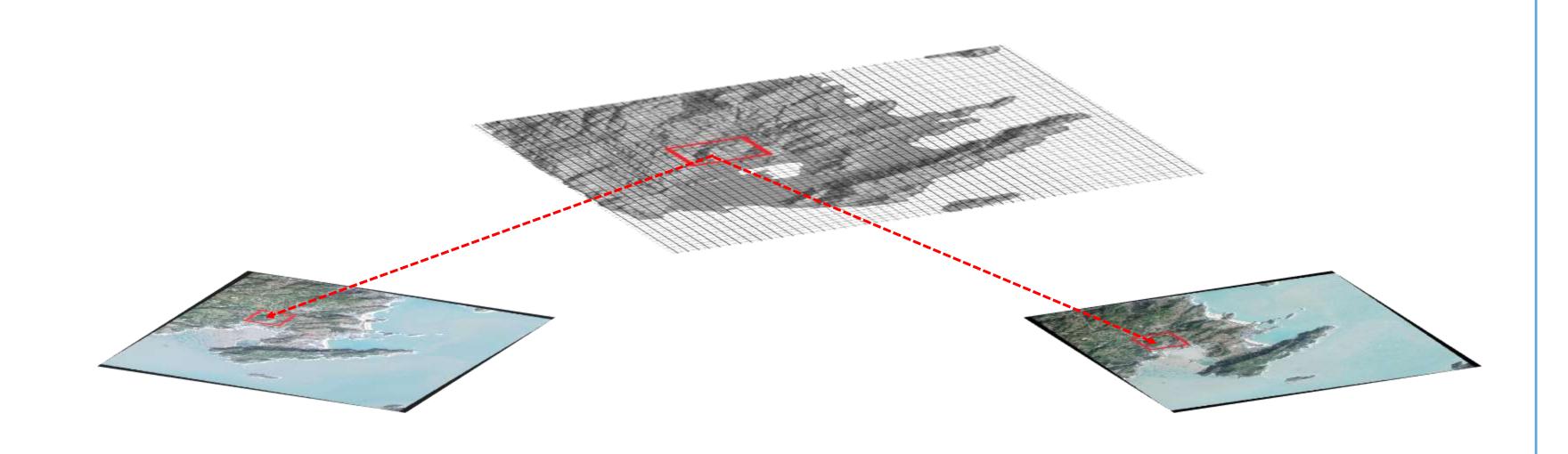
# Efficient Multiview Satellite Stereo

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#### Goal

- Enabling use of multi-pass satellite images
- By-pass limitation of RPC camera models
- Boost efficiency of dense satellite stereo problems
- Leveraging semantics to improve stereo accuracy

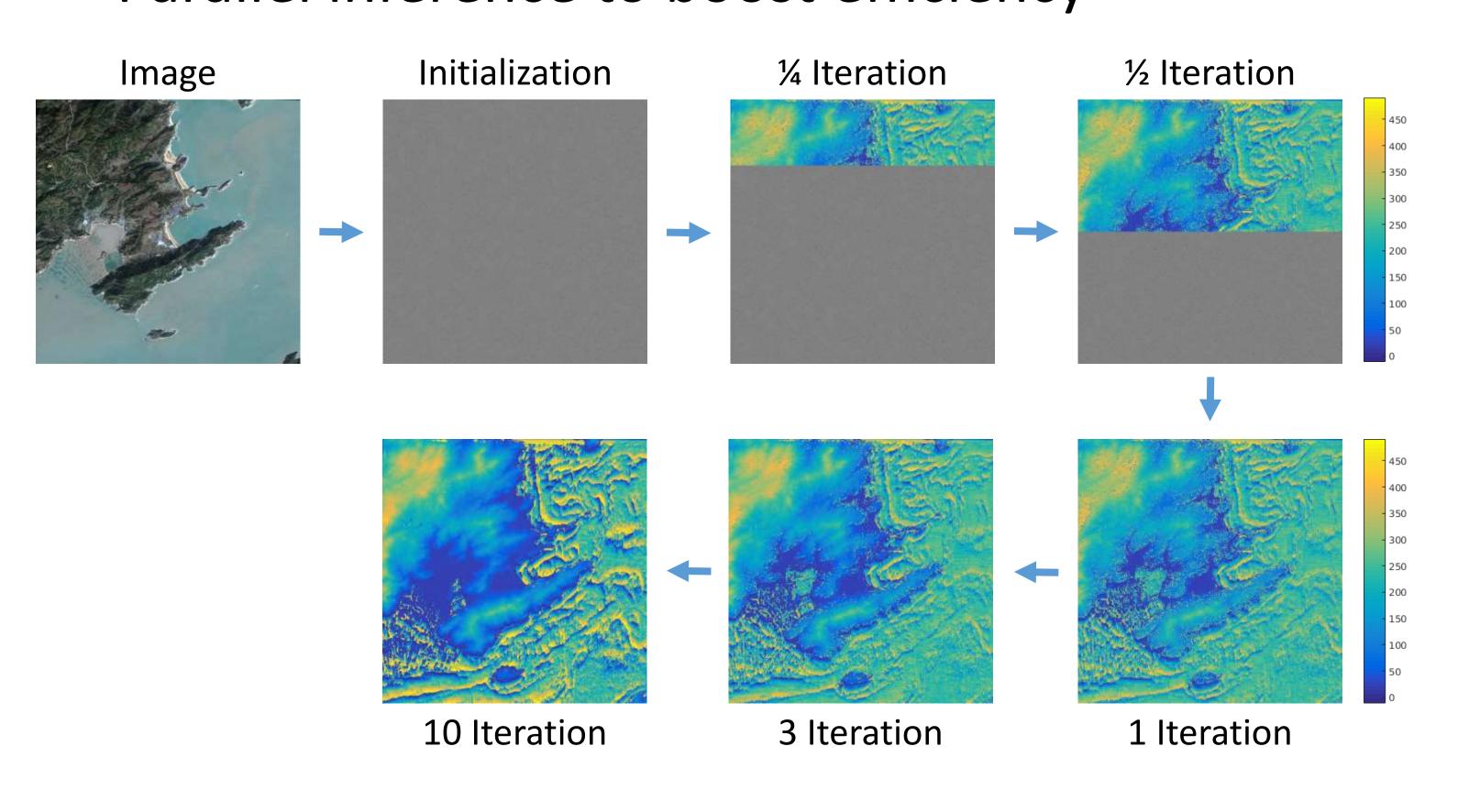
### Formulation



- Represent geospatial region by a vector grid
- Fit a local 3D plane at each grid point
- Project local plane to satellite image to accumulate photo-consistency
- Enforce smoothness amongst nearby planes
- Formulate an MRF over the vector grid
- Enforce smoothness of semantic labels in MRF

# Optimization

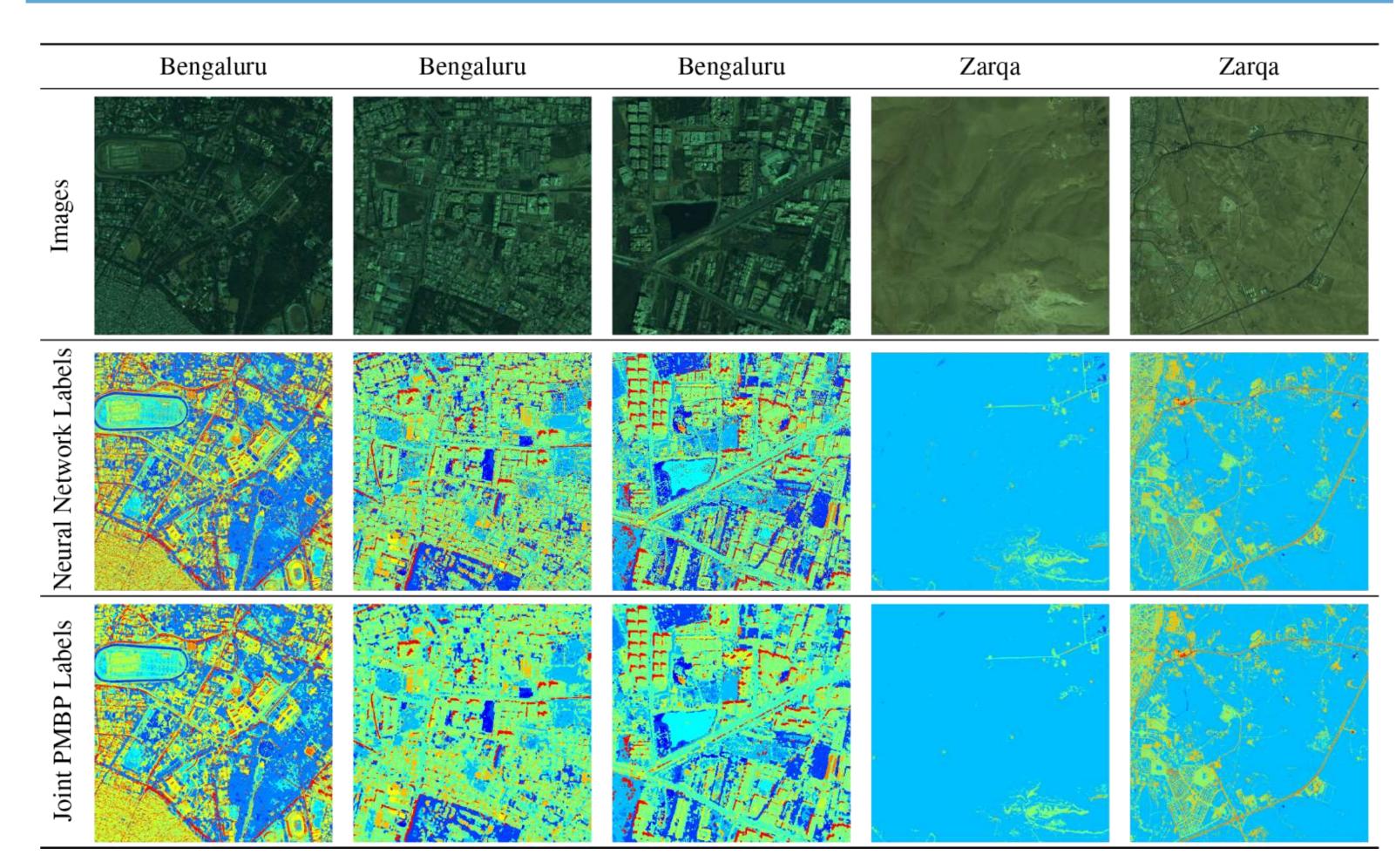
- Predict raw satellite semantic labels by neural networks
- MRF inference via PatchMatch Belief Propagation
- Parallel inference to boost efficiency



### Performance

	Dataset	Resolution	View	SGM	BidPMBP	GridPMBP
Time	Xiapu	26.2 Mpx	2	0.48 Hours	0.57 Hours	<b>0.18</b> Hours
	Bengaluru	66.1 Mpx	5	<b>9.73 Hours</b>	<b>5.75 Hours</b>	<b>1.78</b> Hours
	Zarqa	58.7 Mpx	7	12.96 Hours	7.66 Hours	<b>2.37</b> Hours
Memory	Xiapu	26.2 Mpx	2	1.8 GB	<b>1.4</b> GB	<b>1.4</b> GB
	Bengaluru	66.1 Mpx	5	11.3 GB	<b>8.8</b> GB	<b>8.8</b> GB
	Zarqa	58.7 Mpx	7	12.0 GB	<b>9.4</b> GB	<b>9.4</b> GB

### Semantic Map



## Height Map

